

# **PXIe-6570**





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PXIe-6570 Specifications.
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# PXIe-6570 Specifications

These specifications apply to the PXIe-6570. When using the PXIe-6570 in the Semiconductor Test System, refer to the **Semiconductor Test System Specifications**.

## Definitions

**Warranted** specifications describe the performance of a model under stated operating conditions and are covered by the model warranty. Warranted specifications account for measurement uncertainties, temperature drift, and aging. Warranted specifications are ensured by design or verified during production and calibration.

The following characteristic specifications describe values that are relevant to the use of the model under stated operating conditions but are not covered by the model warranty.

- **Typical** specifications describe the performance met by a majority of models.
- **Nominal** specifications describe an attribute that is based on design, conformance testing, or supplemental testing.

## Conditions

Specifications are valid under the following conditions unless otherwise noted.

- Operating temperature of 0 °C to 45 °C
- Operating temperature within ±5 °C of the last self-calibration temperature
- Recommended calibration interval of 1 year. The PXIe-6570 will not meet specifications unless operated within the recommended calibration interval.
- DUT Ground Sense (DGS) same potential as the Ground (GND) pins



**Note** The DGS feature is only available on PXIe-6570 module revisions 158234**C**-xxL or later.

 Chassis fans set to the highest setting if the PXI Express chassis has multiple fan speed settings

30-minute warmup time before operation

**Note** When the pin electronics on the PXIe-6570 are in the disconnect state, some I/O protection and sensing circuitry remain connected. Do not subject the PXIe-6570 to voltages beyond the supported measurement range.

## General

Channel count	32	
Multi-site resources per instrument	·	
NI-Digital 16.0	4	
NI-Digital 17.0 and later	8	
System channel count <sup>[1]</sup>	256	
Large Vector Memory (LVM)	128M vectors	
History RAM (HRAM)		
NI-Digital 17.5 and earlier	1,023 cycles	
NI-Digital 18.0 and later	(8,192/N sites)-1 cycles	
Maximum allowable offset (DGS minus GND)	±300 mV	

Supported measurement range <sup>[2]</sup>	-2 V to 7 V[3]

## Timing

## **Vector Timing**

Maximum vector rate	100 MHz	
Vector period range	10 ns to 40 μs (100 MHz to 25 kHz)	
Vector period resolution	38 fs	
Timing control		
Vector period	Vector-by-vector on the fly	
Edge timing	Per channel, vector-by-vector on the fly	
Drive formats	Per channel, vector-by-vector on the fly	

## Clocking

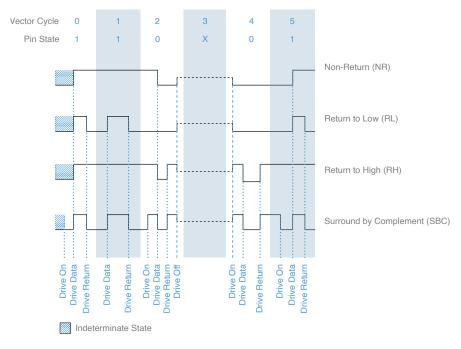
Master clock source	PXIe_CLK100 <sup>[4]</sup>
Sequencer clock domains	One (independent sequencer clock domains on a single instrument not supported)

## **Drive and Compare Formats**

Drive formats <sup>[5]</sup>	
100 MHz maximum vector rate	Non-Return (NR), Return to Low (RL), Return to High (RH)

50 MHz maximum vector rate	Surround by Complement (SBC)[6]	
Compare formats	Edge strobe	
Edge Multipliers <sup>[5]</sup>		
NI-Digital 17.5 and earlier	1x	
NI-Digital 18.0 and later	1x, 2x	

#### Figure 1. Drive Formats



2 Vector Cycle 10 XX 01 00 Pin State Non-Return (NR) Return to Low (RL) Return to High (RH) Drive On 7 Drive Data Drive Return Drive Data 2 hrive Return 2 Drive Off Drive Data Drive Return Drive Data 2 Drive Data ive Return 2 Drive Dat: Drive Data Drive Data Drive Retu **Drive Retu** Indeterminate State

#### Figure 2. 2x Mode Drive Formats

#### **Pin Data States**

#### Pin States

- 0 Drive zero.
- 1 Drive one.
- L Compare low.
- H Compare high.
- X Do not drive; mask compare.
- M Compare midband, not high or low.
- V Compare high or low, not midband; store results from capture functionality if configured.
- D Drive data from source functionality if configured.
- E Expect data from source functionality if configured.<sup>[7]</sup>

• - Repeat previous cycle. Do not use a dash (-) for the pin state on the first vector of a pattern file unless the file is used only as a target of a jump or call operation.

**Note** Termination mode settings affect the termination applied to all nondriving pin states. Non-drive states include L, H, M, V, X, E, and potentially -. Refer to the <u>Programmable input termination mode</u> specification for more information.

## **Edge Timing**

Edge Types

Drive edges		
NI-Digital 17.5 and earlier	4; drive on, drive data, drive return	
NI-Digital 18.0 and later	6; drive on, drive data, drive return, drive data 2, drive return 2, drive off	
Compare edges		
NI-Digital 17.5 and earlier	1; strobe	
NI-Digital 18.0 and later	2; strobe, strobe 2	
Number of time sets <sup>[8]</sup>	31	

#### Edge Generation Timing

Edge placement range	
Minimum	Start of vector period (0 ns)
Maximum	5 vector periods or 40 μs, whichever is smaller
Minimum required edge sepa	ration
Between any driven data chai	nge

NI-Digital 17.5 and earlier	5 ns
NI-Digital 18.0 and later	3.75 ns
Between any Drive On and Drive Off edges	5 ns
Between Compare Strobes	5 ns
Edge placement resolution	39.0625 ps
Edge placement accuracy: Drive <sup>[9]</sup>	
NI-Digital 17.5 and earlier	
Edge Multiplier = 1x	±500 ps, warranted
NI-Digital 18.0 and later	
Edge Multiplier = 1x	±500 ps, warranted
Edge Multiplier = 2x	Bit rate ≤ 200 Mbps: ±500 ps, typical
Edge Multiplier = 2x	Bit rate ≤ 266 Mbps: ±600 ps, typical
Edge placement accuracy: Compare <sup>[9]</sup>	
NI-Digital 17.5 and earlier	
Edge Multiplier = 1x	±500 ps, warranted
NI-Digital 18.0 and later	
Edge Multiplier = 1x	±500 ps, warranted
Edge Multiplier = 2x	Bit rate ≤ 100 Mbps: ±500 ps, typical
Edge Multiplier = 2x	Bit rate ≤ 133 Mbps: ±700 ps, typical
Overall timing accuracy <sup>[9]</sup>	

NI-Digital 17.5 and earlier		
Edge Multiplier = 1x	±1.5 ns, warranted	
NI-Digital 18.0 and later		
Edge Multiplier = 1x	±1.5 ns, warranted	
Edge Multiplier = 2x	Bit rate ≤ 200 Mbps: ±1.5 ns, typical	
Edge Multiplier = 2x	Bit rate ≤ 266 Mbps: ±1.8 ns, typical	
TDR deskew adjustment resolution	39.0625 ps	

## Driver, Comparator, Load

## Driver

Signal type	Single-ended, referenced to the DGS pin when connected. Otherwise referenced to GND.
Programmable levels	V <sub>IH</sub> , V <sub>IL</sub> , V <sub>TERM</sub>
Voltage levels	
Range (V <sub>IH</sub> , V <sub>IL</sub> , V <sub>TERM</sub> )	-2 V to 6 V
Minimum swing (V <sub>IH</sub> minus V <sub>IL</sub> )	400 mV, into a 1 M $\Omega$ load
Resolution (V <sub>IH</sub> , V <sub>IL</sub> , V <sub>TERM</sub> )	122 μV
Accuracy (V <sub>IH</sub> , V <sub>IL</sub> , V <sub>TERM</sub> )	$\pm 15$ mV, 1 M $\Omega$ load, warranted
Maximum DC drive current	±32 mA

Output impedance	50 Ω
Rise/fall time, 20% to 80%	1.2 ns, up to 5 V

## Comparator

Signal type	Single-ended, referenced to the DGS pin when connected. Otherwise referenced to GND.
Programmable levels	V <sub>OH</sub> , V <sub>OL</sub>
Voltage levels	
Range (V <sub>OH</sub> , V <sub>OL</sub> )	-2 V to 6 V
Resolution (V <sub>OH</sub> , V <sub>OL</sub> )	122 μV
Accuracy (V <sub>OH</sub> , V <sub>OL</sub> )	±25 mV, from -1.5 V to 5.8 V, warranted
Programmable input termination modes	High Z, 50 $\Omega$ to $V_{TERM},$ Active Load
Leakage current	<15 nA, in the High Z termination mode

## **Active Load**

Programmable levels	I <sub>OH</sub> , I <sub>OL</sub>
Commutating voltage (V <sub>COM</sub> )	
Range	-2 V to 6 V
Resolution	122 μV

Current levels		
Range	1.5 mA to 24 mA	
Resolution	488 nA	
Accuracy	1 mA, 3 V over/under drive, typical	

## PPMU

## **PPMU Force Voltage**

Signal type	Single-ended, referenced to the DGS pin when connected. Otherwise referenced to GND.
Voltage levels	
Range	
NI-Digital 17.5 and earlier	-2 V to 6 V
NI-Digital 18.0 and later	-2 V to 6 V 6 V to 7 V in Extended Voltage Range <sup>[10]</sup>
Resolution	122 μV
Accuracy	
NI-Digital 17.5 and earlier	$\pm 15$ mV, 1 M\Omega load, from -2 V to 6 V, warranted
NI-Digital 18.0 and later	$\pm 15$ mV, 1 MΩ load, from -2 V to 6 V, warranted $\pm 50$ mV, 1 MΩ load, from 6 V to 7 V, typical <sup>[10]</sup>

#### **PPMU Measure Voltage**

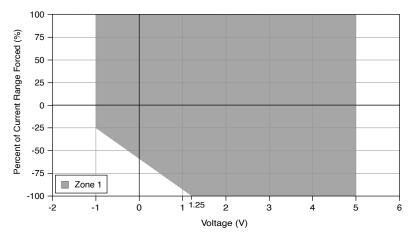
Signal type	Single-ended, referenced to the DGS pin when connected. Otherwise referenced to GND.
Voltage levels	
Range	-2 V to 6 V
Resolution	228 μV
Accuracy	±5 mV, warranted

#### **PPMU Force Current**

#### How to Calculate PPMU Force Current Accuracy

Table 1. PPMU Force Current Accuracy
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Range	Resolution	Accuracy
±2 μA	60 pA	±1% of range for Zone 1 of
±32 μA	980 pA	Figure 3, warranted
±128 μA	3.9 nA	
±2 mA	60 nA	
±32 mA	980 nA	



#### Figure 3. Warranted Current Accuracy Zone for PPMU Force Current

**Note** The boundaries of Zone 1 are inclusive of that zone. The area outside of Zone 1 does not have a warranted spec for PPMU force current accuracy.

- 1. Specify the desired forced current.
- 2. Based on the desired forced current, select an appropriate current range from Table 1.
- 3. Divide the desired forced current from step 1 by the current range from step 2 and multiply by 100 to calculate the Percent of Current Range Forced.
- 4. Based on the impedance of the load, calculate the voltage required to force the desired current from step 1. Use the following equation: Voltage Required = Desired Current \* Load Impedance.
- 5. Using Figure 2, locate the zone in which the Percent of Current Range Forced calculated in step 3 intersects with the Voltage calculated in step 4. If the intersection is outside of Zone 1, then there are no warranted specs. To get warranted specs, the current range and/or forced current must be adjusted until the intersection is in Zone 1.
- 6. Based on the zone found in step 5, use Table 1 to calculate the accuracy of the forced current.

PPMU voltage clamps		
Range	-2 V to 6 V	

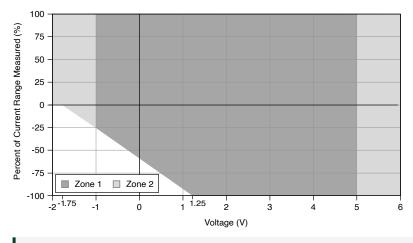
Resolution	122 μV
Accuracy	±100 mV, typical

#### **PPMU Measure Current**

#### How to Calculate PPMU Measure Current Accuracy

Range	Resolution	Accuracy
±2 μA	460 pA	±1% of range for Zone 1 of
±32 μA	7.3 nA	<u>Figure 4</u> , warranted
±128 μA	30 nA	±1.5% of range for Zone 2 of
±2 mA	460 nA	Figure 4, warranted
±32 mA	7.3 μΑ	

Figure 4. Warranted Current Accuracy Zones for PPMU Measure Current



**Note** The boundaries of Zone 1 are inclusive of that zone. All other boundaries are inclusive of Zone 2. The area outside of Zone 1 and Zone 2 does not have a warranted spec for PPMU measure current accuracy.

1. Specify the desired measured current.

- 2. Based on the desired measured current, select an appropriate current range from Table 2.
- 3. Divide the desired measured current from step 1 by the current range from step 2 and multiply by 100 to calculate the Percent of Current Range Measured.
- 4. If forcing voltage and then measuring current, Voltage in Figure 3 is equal to the forced voltage. If forcing current and then measuring current, Voltage in Figure 3 is equal to the voltage required to force the desired current based on the impedance of the load. Use the following equation: Voltage Required = Desired Current \* Load Impedance.
- 5. Using Figure 3, locate the zone in which the Percent of Current Range Measured calculated in step 3 intersects with the Voltage calculated in step 4. If the intersection is outside of Zone 1 or Zone 2, then there are no warranted specs. To get warranted specs, the current range and forced current or forced voltage must be adjusted until the intersection is in Zone 1 or Zone 2.
- 6. Based on the zone found in step 5, use Table 2 to calculate the accuracy of the measured current.

#### PPMU Programmable Aperture Time

Aperture time	
Minimum	4 μs
Maximum	65 ms
Resolution	4 μs

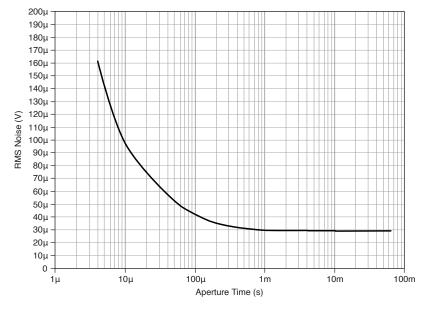


Figure 5. Voltage Measurement Noise for Given Aperture Times, Typical

## **Pattern Control**

## Opcodes

Refer to the following table for supported opcodes. Using matched and failed opcode parameters with multiple PXIe-6570 instruments requires the PXIe-6674T synchronization module. Other uses of flow-control opcodes with multiple PXIe-6570 instruments only require NI-TCLK synchronization.

Category	Supported Opcodes
Flow Control	<ul> <li>repeat</li> <li>jump</li> <li>jump_if</li> <li>set_loop</li> <li>end_loop</li> <li>exit_loop</li> <li>exit_loop_if</li> <li>call</li> <li>return</li> </ul>

Category	Supported Opcodes
	keep_alive
	<ul> <li>match</li> </ul>
	<ul> <li>halt</li> </ul>
Sequencer Flags and Registers	<ul> <li>set_seqflag</li> </ul>
	<ul> <li>clear_seqflag</li> </ul>
	<ul> <li>write_reg</li> </ul>
Signal	<ul> <li>set_signal</li> </ul>
	<ul> <li>pulse_signal</li> </ul>
	<ul> <li>clear_signal</li> </ul>
Digital Source and Capture	<ul> <li>capture_start</li> </ul>
	<ul> <li>capture</li> </ul>
	<ul> <li>capture_stop</li> </ul>
	<ul> <li>source_start</li> </ul>
	<ul> <li>source</li> </ul>
	<ul> <li>source_d_replace</li> </ul>
	<ul><li>source_start</li><li>source</li></ul>

**Note** The source\_d\_replace opcode is only available with NI-Digital 18.0 or later.

## **Pipeline Latencies**

Minimum delay between source_start opcode and the first source opcode or subsequent source_start opcode	3 μs
Matched and failed condition pipeline latency	80 cycles

## Source and Capture

Digital Source <sup>[11]</sup>		
Operation modes	Serial and parallel; broadcast and site-unique	
Source memory size	32 MB (256 Mbit) total	
Maximum waveforms	512	
Digital Capture <sup>[11]</sup>		
Operation modes	Serial and parallel; site-unique	
Capture memory size	1 million samples	
Maximum waveforms	512	

## **Independent Clock Generators**

## **Note** This functionality requires NI-Digital 18.0 or later.

Number of Clock Generators	32 (one per pin)
Clock Period Range	6.25 ns to 40 us (160 MHz to 25 kHz) <sup>[12]</sup>
Clock Period Resolution	38 fs

### **Frequency Measurements**



**Note** This functionality requires NI-Digital 17.0 or later.

Frequency counter measure frequency	
Range	5 kHz to 200 MHz, 2.5 ns minimum pulse width
Accuracy	See <u>Calculating Frequency Counter Error</u>

#### **Calculating Frequency Counter Error**

Use the following equation to calculate the frequency counter error (ppm).

 $\left(\frac{TB_{err}}{(1 - TB_{err})} + \frac{20ns}{(MeasurementTime - UnknownClockPeriod)}\right) * 1,000,000$ where

- MeasurementTime is the time, in seconds, over which the frequency counter measurement is configured to run
- UnknownClockPeriod is the time, in seconds, of the period of the signal being measured
- TB<sub>err</sub> is the error of the Clk100 timebase

Refer to the following table for a few examples of common Clk100 timebase accuracies.

Table 3. TBerr

PXI Express Hardware Specification Revision 1.0	PXIe-1085 Chassis	PXIe-6674T Override
100 μ (100 ppm)	25 μ (25 ppm)	80 n (80 ppb)

## Example 1: Calculating Error with a PXIe-1085 Chassis

Calculate the error of performing a frequency measurement of a 10 MHz clock (100 ns period) with a 1 ms measurement time using the PXIe-Clk100 provided by the PXIe-1085 chassis as the timebase.

Solution

$$\left(\frac{25\mu}{(1-25\mu)} + \frac{20ns}{(1ms - 100ns)}\right) * 1,000,000$$
  
= 45*ppm*

# Example 2: Calculating Error when Overriding with the PXIe-6674T

Calculate the error if you override the PXIe-Clk100 timebase with the PXIe-6674T and increase the measurement time to 10 ms.

Solution

 $\left(\frac{80n}{(1-80n)} + \frac{20ns}{(10ms - 100ns)}\right) * 1,000,000$ = 2ppm

## **Calibration Interval**

Recommended calibration interval	1 year

## **Physical Characteristics**

PXIe slots	2
Dimensions	131 mm × 42 mm × 214 mm (5.16 in. × 1.65 in. × 8.43 in.)
Weight	920 g (32.45 oz.)

### **Power Requirements**

The PXIe-6570 draws current from a combination of the 3.3 V and 12 V power rails. The maximum current drawn from each of these rails can vary depending on the PXIe-6570 mode of operation. The total power consumption will not exceed the input power specification.

Input power	68 W
Current Draw	
3.3 V	4.4 A
12 V	4.7 A